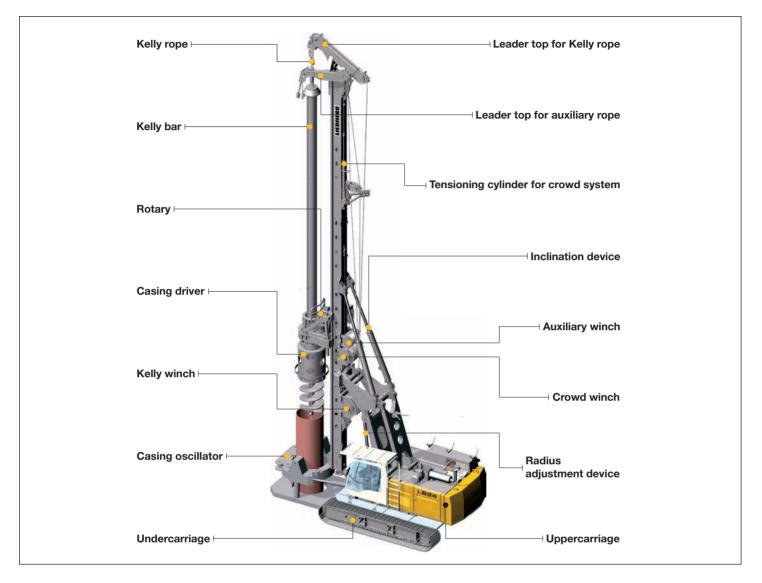


# LIEBHERR

## **Concept and characteristics**

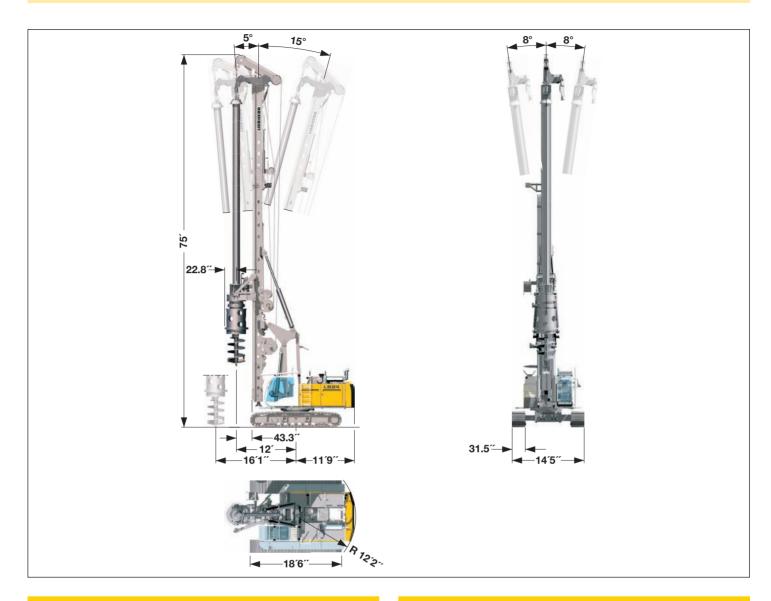


- High engine output with automatic engine speed control
- Controlled entirely from cab
- Sturdy and solid rig design
- Solid parallel kinematics on the basic machine
- High pull and push forces
- High torque
- Completely self-rigging (no auxiliary machines required)
- Large range of working tools (all common drilling works can be performed)
- Stepless leader inclination 5° forward 15° backward depending on type of equipment
- Automatic vertical alignment

- High alignment forces
- Simultaneous control of several movements via Loadsensing multi-circuit hydraulics
- Quick assembly of rotary possible through quick connection
- Equipment design according to latest European regulations and standards
- All components designed to fulfill the special requirements of a drilling rig
- High manufacturing quality through quality control by PDE®-system

## **Dimensions**

### Basic machine LB 24

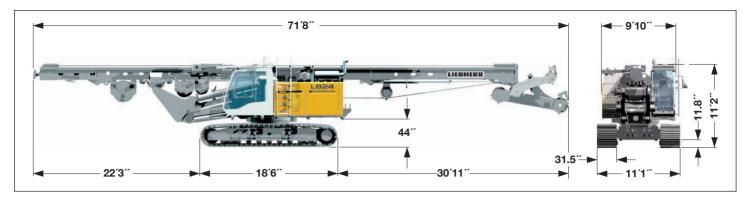


Technical data	
Total height —	—— 75 ft
Max. pull, leader on ground ————————————————————————————————————	*
Stepless leader inclination  Lateral inclination  Forward inclination  Backward inclination	± 8° 5° 15°

<b>Operating</b>	weight
Total weight ——	with 27.6 inch 3-web shoes — 165,350 lbs
	with 31.5 inch 3-web shoes — 166,450 lbs
	with 35.4 inch 3-web shoes — 167,550 lbs

The operating weight includes the basic machine (with rotary and Kelly bar MD 28/3/24) and 22,490 lbs counterweight.

## **Transport dimensions and weights**

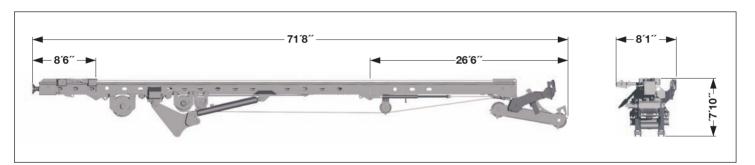


#### **Transport with leader**

includes the basic machine (ready for operation) with leader, without working tools (such as rotary, Kelly bar etc.) and without counterweight.

#### **Dimensions and weights**

Leader length —	— 63.7 ft
Weight complete without counterweight	119,300 lbs



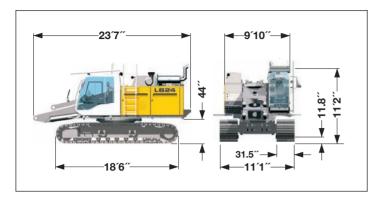
#### **Transport leader**

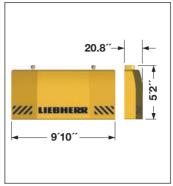
includes the leader without working tools (such as rotary, Kelly bar etc.).

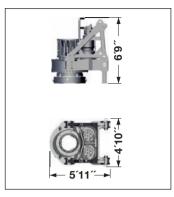
#### **Dimensions and weights**

Leader length —	63.7 ft
Weight complete —	41,230 lbs
Lower part of the leader	2,645 lbs
Upper part of the leader with leader top —	6,615 lbs

# **Transport dimensions and weights**







# **Transport basic machine**ready for operation, without counterweight. Transport weight — 78,045 lbs

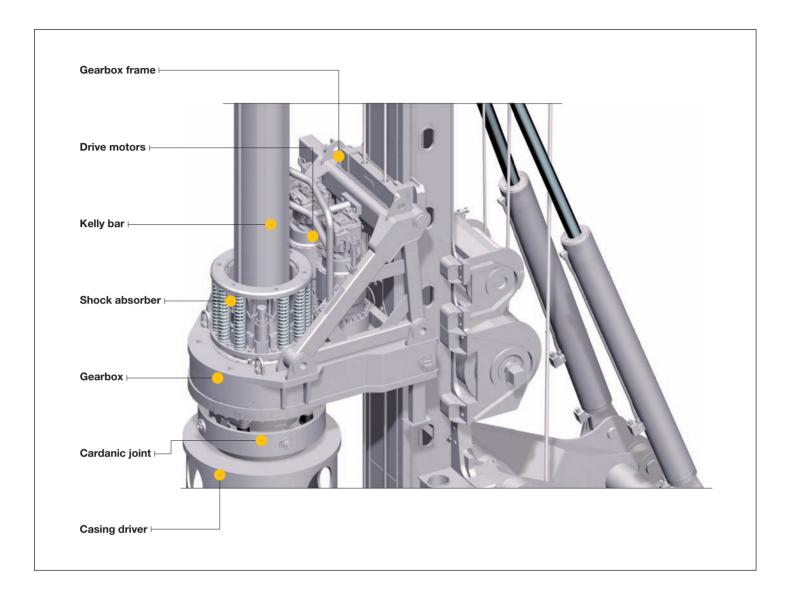


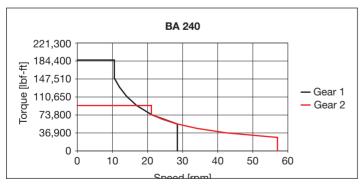
Rotary
Transport weight
BA 240 — 13,670 lbs

Weights can vary with the final configuration of the machine.

The figures in this brochure may include options which are not within the standard scope of supply of the machine.

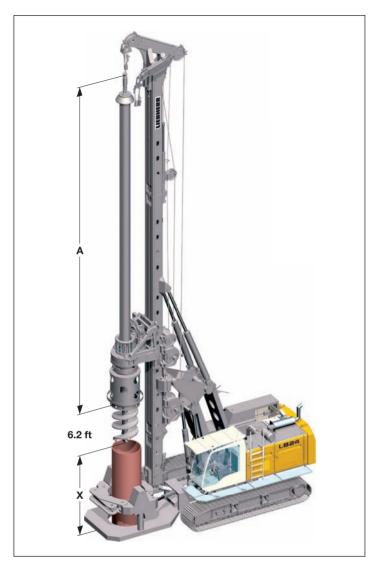
## Rotary BA 240 with shock absorber

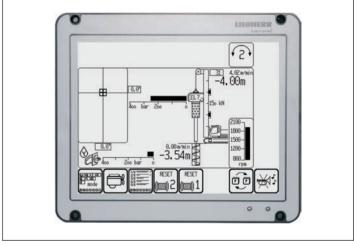




- 2-stage-gear drive for flexible adaptation to soil conditions
- Due to stepless speed control via joystick optimum and precise alignment and rock drilling is possible even at low speed levels; it is not required to preselect an operating mode
- Kelly shock absorber and rubber bearing relieve the material and reduce noise emission
- Thanks to the Kelly shock absorber the Kelly bar is guided at greater length
- Various drive adapters provide compatibility with other systems

# **Kelly drilling**





Display for Kelly drilling

## **Technical data**

	- 1st gear — 185,900 lbf-ft
Drilling drive - speed —	- 1 <sup>st</sup> gear 28 rpm
Drilling drive - torque	2 <sup>nd</sup> gear — 92,950 lbf-ft
Drilling drive - speed -	2 <sup>nd</sup> gear — 57 rpm

#### **Performance data**

Max. drilling diameter*	6.2 ft uncased
Max. drilling diameter* ——	4.9 ft cased

<sup>\*)</sup> Other drilling diameters available on request.

### **Kelly bars**

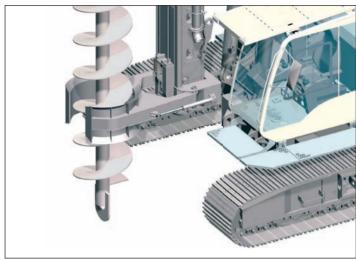
A X Drilling depth Weight Kelly Ø  (ft) (ft) (ft) (ft) (lbs) (inch)  MD 28/3/24 32.4 27.9 72.2 11,030 16.5  MD 28/3/27 35.7 24.6 82.0 12,125 16.5  MD 28/3/30 39.0 21.3 91.9 13,010 16.5	
MD 28/3/24     32.4     27.9     72.2     11,030     16.5       MD 28/3/27     35.7     24.6     82.0     12,125     16.5       MD 28/3/30     39.0     21.3     91.9     13,010     16.5	j
MD 28/3/27 35.7 24.6 82.0 12,125 16.5 MD 28/3/30 39.0 21.3 91.9 13,010 16.5	
MD 28/3/30 39.0 21.3 91.9 13,010 16.5	
ND 00/0/00 400 400 4017 44440 405	
MD 28/3/33   42.3   18.0   101.7   14,110   16.5	
MD 28/3/36 45.5 14.8 111.5 15,000 16.5	
MD 28/4/36 37.6 22.6 111.5 15,875 16.5	
MD 28/4/42 42.5 17.7 131.2 17,860 16.5	
MD 28/4/48 47.4 12.8 150.9 19,845 16.5	
MD 28/4/54 52.3 7.9 170.6 21,605 16.5	
MD 28/4/60 57.3 2.9 190.3 23,590 16.5	

Other Kelly bars available on request.

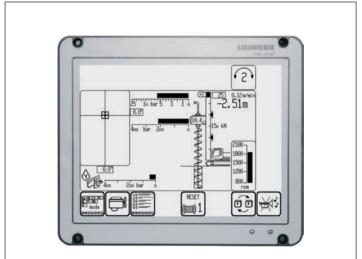
When using a casing oscillator, value X has to be reduced by 4.9 ft.

# **Continuous flight auger drilling**





Auger with auger guide



Display for continuous flight auger drilling

Technical data	
Drilling drive - torque -	— 1st gear —— 185,900 lbs-ft
Drilling drive - speed -	— 1 <sup>st</sup> gear ———— 28 rpm
Drilling drive - torque	- 2 <sup>nd</sup> gear 92,950 lbs-ft
Drilling drive - speed —	- 2 <sup>nd</sup> gear 57 rpm

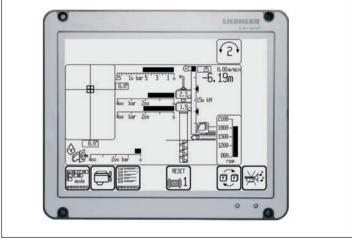
Performance data		
Drilling depth with auger cleaner*	— 49. <del>.</del>	5 ft
Drilling depth without auger cleaner*	— 51.	2 ft
Drilling depth with 19.7 ft Kelly extension, without auger cleaner	— 70.º	9 ft
Max. pull force (crowd winch and Kelly winch)	161,90	0 lbf
Max. push force (weight of rotary and auger to be added)	33,75	0 lbf
Max. drilling diameter**	3.5	3 ft

- \*) Without Kelly extension
  \*\*) Other drilling diameters available on request.

# **Double rotary drilling**

### **Model DBA 80**





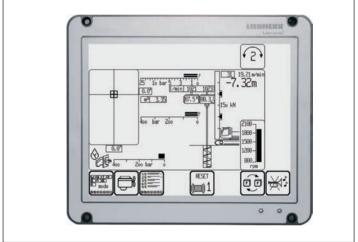
Display for double rotary drilling

Technical data		
Drilling drive I - torque — — — — — — — — — — — — — — — — — — —	0	′
Drilling drive I - torque — — — — Drilling drive I - speed — — — — — — — — — — — — — — — — — —	•	
Drilling drive II - torque ————————————————————————————————————	-	
Drilling drive II - torque ————————————————————————————————————		
Max. drilling diameter*		24.4 inch
Max. drilling depth		—— 50.5 ft
Max. pull force		— 112,400 lbf

<sup>\*)</sup> Other drilling diameters available on request.

# Twin mix equipment Model DMA 35





Display for soil mixing

Technical date		
Drilling drive - torque — Drilling drive - speed —	1 <sup>st</sup> gear 1 <sup>st</sup> gear	——— 25,850 lbf-ft ———— 38 rpm
Drilling drive - torque — Drilling drive - speed —	•	——— 12,910 lbf-ft ———— 76 rpm
Max. drilling depth ——		50.5 ft
Max. drilling diameter* —		27.6 inch

<sup>\*)</sup> Other diameters available on request.

## **Technical description**



#### **Engine**

Power rating according to ISO 9249, 270 kW (362 hp) at 2000 rpm Engine type — Liebherr D 936 L A6

Fuel tank — 185 gal capacity with continuous level indicator and reserve warning

Engine complies with NRMM exhaust certification EPA/CARB Tier 3 and 97/68 EC Stage III A.



#### **Hydraulic system**

The main pumps are operated by a distributor gearbox. Axial piston displacement pumps work in open circuits supplying oil only when needed (flow control on demand). The hydraulic pressure peaks are absorbed by the integrated automatic pressure compensation, which relieves the pump and saves fuel.

Pumps for working tools —	2x 63 gal/min
Separate pump for kinematics ————	36 gal/min
Hydraulic oil tank —	159 gal
Max. working pressure —	5076 PSI

The cleaning of the hydraulic oils occurs via an electronically monitored pressure and return filter. Any clogging is shown on the monitor in the cab. The use of synthetic environmentally friendly oil is also possible.



#### Crawlers

Propulsion through axial piston motor, hydraulically released spring loaded multi-disc brake, maintenance free crawler tracks, hydraulic chain tensioning device.

Drive speed of telescopic undercarriage —————	0 - 0.68  mph
Track force —	142,530 lbf
Width of 3-web track shoes —	— 31.5 inch
Transport width —	— 11.15 ft
Option:	
Width of 3-web track shoes	— 27.6 inch
Transport width —	— 9.84 ft
Width of 3-web track shoes —	— 35.4 inch
Transport width —	— 11.45 ft



#### Swing

Consists of triple-row roller bearing with external teeth and one swing drive, fixed axial piston hydraulic motors, spring loaded and hydraulically released multi-disc holding brake, planetary gearbox and pinion. Selector for 3 speed ranges to increase swing precision.

Swing speed from 0 – 3.5 rpm is continuously variable.



#### Control

The control system - developed and manufactured by Liebherr - is designed to withstand extreme temperatures and the many heavy-duty construction tasks for which this machine has been designed. Complete machine operating data are displayed on a high resolution monitor. A GSM modem allows for remote inquiry of machine data and error indications. To ensure clarity of the information on display, different levels of data are shown in enlarged lettering and symbols. Control and monitoring of the sensors are also handled by this high technology system. Error indications are automatically displayed on the monitor in clear text. The machine is equipped with proportional control for all movements, which can be carried out simultaneously. Two joysticks are required for operation. Pedal control can be changed to hand control.

#### Options:

- · PDE: Process data recording
- GSM modem

#### † **\*///**

#### Kelly winch with freewheeling

Line pull effective (2 <sup>nd</sup> layer) -	44,960 lbf
Rope diameter ————	28 mm
Line speed —	0-259 ft/min



### **Auxiliarvy winch**

Line pull effective (1st layer)	17,985 lbf
Rope diameter —	— 20 mm
Line speed —	0-233 ft/min



#### **Rope crowd system**

Crowd force (push/pull) -	72,000/72,000 lbf
Line pull (effective) ——	36,000 lbf
Rope diameter —	24 mm
Travel of working tool -	52.5 ft
Line speed —	0-249 ft/min

The winches are noted for compact, easily mounted design. Propulsion is via a maintenance-free planetary gearbox in oil bath. Load support by the hydraulic system; additional safety factor by a spring-loaded, multi-disc holding brake. All line pull values are effective values. The efficiency factor of approx. 25% has already been deducted.

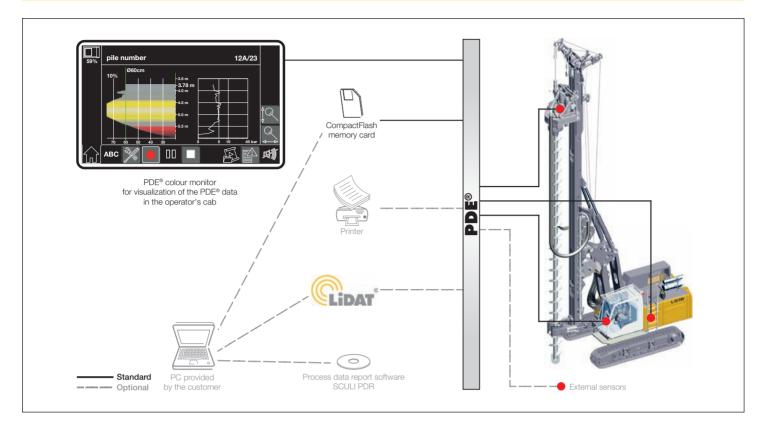


#### Noise emission

Noise emissions correspond with 2000/14/EC directive on noise emission by equipment used outdoors.

## Process data recording system - PDE® (additional equipment)

The Liebherr process data recording system PDE® constantly records the relevant process data during the working process.



Depending on the application the recorded and processed data are displayed on the PDE® touchscreen in the operator's cab, e.g. in the form of an online cast-in-place pile.

At the same time the PDE® is operated using this touchscreen. The operator can enter various details (e.g. jobsite name, pile number, etc.) and start and stop recordings. A recording of every start-stop cycle carried out in the PDE® is established on a CompactFlash memory card.

The PDE® can be configured in a number of ways, e.g. for the connection of external sensors, for the generation of a simple protocol as graphic file and/or for a printout directly in the operator's cab.

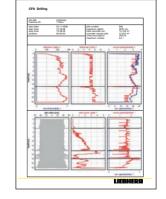
## Process data reporting - PDR (additional equipment)

Comprehensive data evaluation and generation of reports on a PC is possible using the software SCULI PDR.

**Recordings management -** The recordings generated by the PDE® system can be imported and managed in SCULI PDR. The data can be imported directly from the CompactFlash card or via the Liebherr telematics system LiDAT. Certain recordings, e.g. for a particular day or jobsite, can be found using filter functions.

**Viewing data** - The data in each record is displayed tabularly. Combining several recordings provides results, for example, regarding the total concrete consumption or the average depth. Furthermore, a diagram editor is available for quick analysis.

**Generating reports** - A vital element of SCULI PDR is the report generator, which allows for the generation of individual reports. These can be printed out directly or stored as pdf files. In the process the size, colour, line thickness or even the desired logo can be configured. Moreover, the reports can be displayed in different languages, e.g. in English and in the national language.



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