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LB 25

LB 2002.07 www.liebherr.com

LIEBHERR

Drilling rigs



Concept and characteristics







MyJobsite













Kelly visualization



Ground pressure visualization



Radio remote control



Concrete pump

The robust universal machine for a wide variety of applications

- Kelly drilling
- Continuous flight auger drilling
- Full displacement drilling
- Double rotary drilling
- -Soil mixing
- Down-the-hole drilling

Assistance systems

- Cruise Control for all main functions
- -Control lever for all machine functions
- -Automatic shake-off function for working tools
- Kelly visualization
- Ground pressure visualization
- -Radio remote control
- Radio remote control for concrete pump
- Drilling assistant (single-pass process)
- -Leader inclination memory
- -Display of auger filling level
- Kelly winch with freewheeling and with slack rope monitoring and prevention

Technical description



Diesel engine

Power rating according to ISO 9249	320 kW (429 hp) at 1700 rpm
Engine type	Liebherr D 936 A7-05
Fuel tank capacity	700 l with continuous level indicator and reserve warning
Exhaust certification	EU 2016/1628 Stage V EPA/CARB Tier 4f ECE-R.96 Power Band H non-certified emission standard

Hydraulic system

	use of synthetic environmentally friendly oil possible
Hydraulic oil	electronic monitoring of all filters
Max. working pressure	385 bar
Hydraulic oil tank capacity	600 l

Crawlers

Drive system	with fixed axial piston hydraulic motors
Crawler side frames	maintenance-free, with hydraulic chain tensioning device
Brake	hydraulically released, spring-loaded multi-disc holding brake
Drive speed	0-2.0 km/h
Track force	440 kN
Grousers	width 700 mm (option 800 mm)

Swing gear

Drive system	with fixed axial piston hydraulic motors, planetary gearbox, pinion
Swing ring	roller bearing with external teeth
Brake	hydraulically released, spring-loaded multi-disc holding brake
Swing speed	0-3.75 rpm continuously variable

Kelly winch with freewheeling

Line pull effective	200 kN (1st layer)
Rope diameter	28 mm
Rope speed	0-95 m/min

† Auxiliary winch

Line pull effective	80 kN (1st layer)	
Rope diameter	20 mm	
Rope speed	0-82.5 m/min	

† Crowd system

Crowd force	300/300 kN (push/pull)
Line pull effective	150 kN (1st layer)
Rope diameter	24 mm
Travel with standard leader	17.3 m
between mechanical limit stops	
Travel with Ultra-Low-Head leader	4.6 m
and short leader lower part	
Rope speed	0-88 m/min

$\mathfrak{H}_{\text{Noise meas}}$

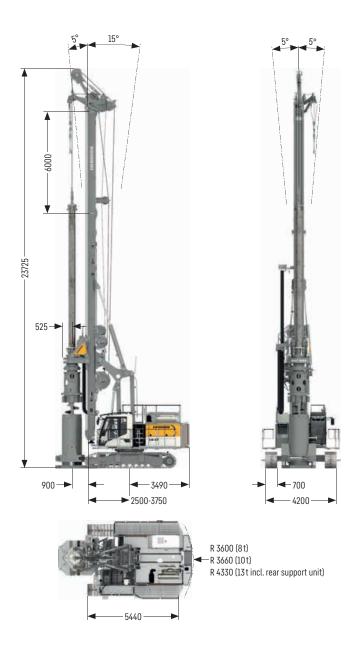
Noise emission	according to 2000/14/EC directive		
Emission sound pressure level Lpa	77.0 dB(A)	(in the cabin)	
Guaranteed sound power level L _{wa}	108 dB(A)	(of the machine)	
Vibration transmitted to the	< 2.5 m/s ²	(to the hand-arm system)	
machine operator	$< 0.5 \text{m/s}^2$	(to the whole body)	
Eco-Silent Mode			
(option)			
Guaranteed sound power level L _{wa}	-3 dB(A)	(of the machine)	

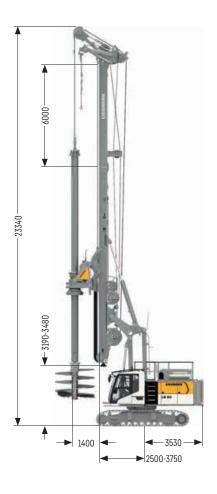
Remarks

- -Illustrations showing the types of application (e.g. Kelly drilling, continuous flight auger drilling etc.) are examples only.
- Weights and transport dimensions can vary with the final configuration of the machine. The figures in this brochure may include options which are not within the standard scope of supply of the machine.

Dimensions

Standard





Operating weights

Total weight with 700 mm 3-web grousers	t 71.2
Total weight with 800 mm 3-web grousers	t 71.6

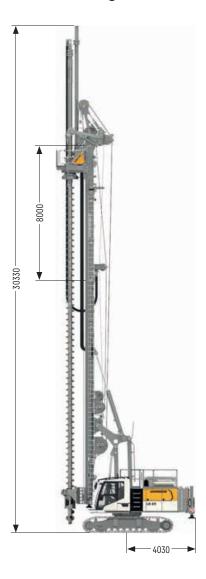
The operating weight includes the basic machine LB 25 with rotary, Kelly bar 20/3/27, 8t counterweight and equipment for casing oscillator.

Operating weights

Total weight with 700 mm 3-web grousers	t 76.7
Total weight with 800 mm 3-web grousers	t 77.1

The operating weight includes the basic machine LB 25 with rotary, Kelly bar 20/4/48 and 10t counterweight. Equipment for casing oscillator not included.

Folding leader



Low Head



Operating weights

Total weight with 700 mm 3-web grousers	t 80.1
Total weight with 800 mm 3-web grousers	† 80.5

The operating weight includes the basic machine LB 25 with rotary, 6m Kelly extension, drill rod 20 m, auger cleaner ø 600 mm and 13t counterweight. Equipment for casing oscillator not included.

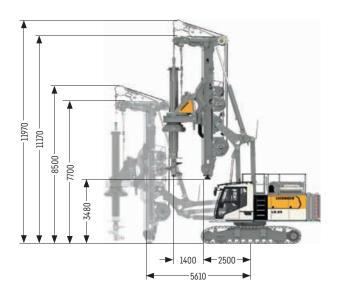
Operating weights

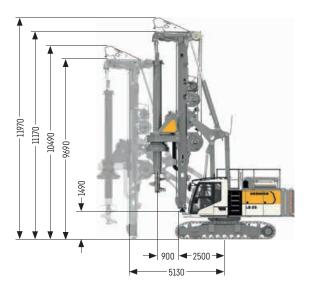
Total weight with 700 mm 3-web grousers	t 68.6
Total weight with 800 mm 3-web grousers	t 69.0

The operating weight includes the basic machine LB 25 with rotary, Kelly bar 20/3/18 and 10t counterweight.

Equipment for casing oscillator not included. The line pull of the Kelly winch is reduced to 160 kN when working at a radius exceeding 3750 mm.

Ultra Low Head





Operating weights

	•		
Total weight with	700 mm 3-web grousers	t	74.7
Total weight with	800 mm 3-web grousers	t	75.1

The operating weight includes the basic machine LB 25 with rotary, Kelly bar 28/3/30, $13\,\mathrm{t}$ counterweight and equipment for casing oscillator.

The line pull of the Kelly winch is reduced to 160 kN when working at a radius exceeding 3750 mm.

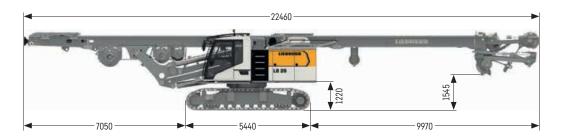
Operating weights

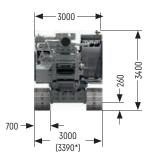
Total weight with 700 mm 3-web grousers	t 75.9
Total weight with 800 mm 3-web grousers	t 76.3

The operating weight includes the basic machine LB 25 with rotary, Kelly bar 28/4/42 and 13t counterweight. Equipment for casing oscillator not included.

The line pull of the Kelly winch is reduced to 160 kN when working at a radius exceeding 3750 mm.

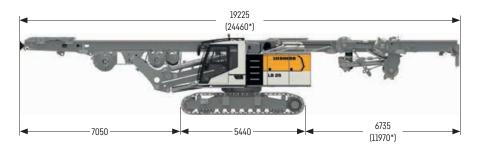
Transport dimensions and weights





Standard leader (6 m leader upper part)

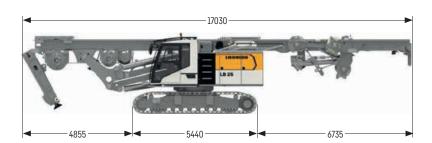
includes the basic machine (fully tanked and ready for operation) with leader, $\;$ t $\;$ 50.4 without attachments (such as rotary, Kelly bar etc.), without counterweight and without adapter for casing oscillator



Folding leader (8 m leader upper part)

includes the basic machine (fully tanked and ready for operation) with leader, t 51.4 without attachments (such as rotary, Kelly bar etc.), without counterweight and without adapter for casing oscillator

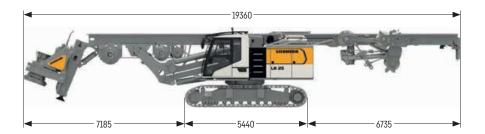
^{*} Transport length leader not folded



Leader lower and upper part folded

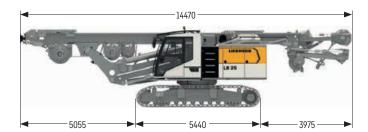
includes the basic machine (fully tanked and ready for operation) with leader, $\ t\ 51.4$ without attachments (such as rotary, Kelly bar etc.), without counterweight and without adapter for casing oscillator

^{*} Transport width with 800 mm grousers



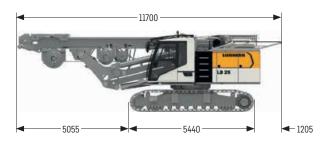
Leader lower and upper part folded (with BAT)

includes the basic machine (fully tanked and ready for operation) with leader, t 57.1 BAT 250, without counterweight and without adapter for casing oscillator



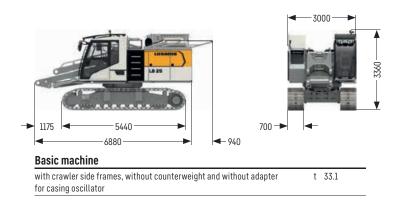
Low Head

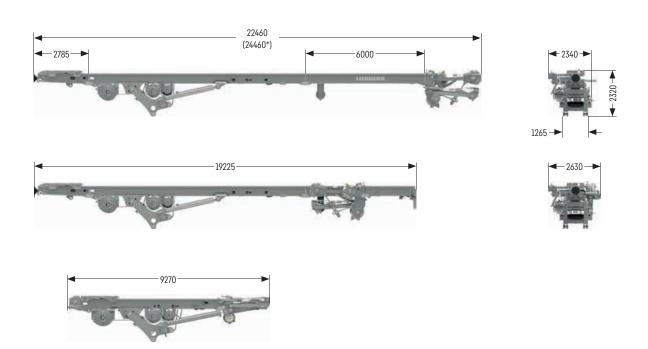
includes the basic machine (fully tanked and ready for operation) with leader, $$ t $$ 48.2 without attachments (such as rotary, Kelly bar etc.), without counterweight and without adapter for casing oscillator



Ultra Low Head

includes the basic machine (ready for operation) with leader, without attachments (such as rotary, Kelly bar etc.), without counterweight and without adapter for casing oscillator





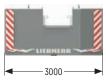
Leader versions

Standard leader	t	17.8
Folding leader	t	18.7
Ultra Low Head (without leader base support)	t	13.4
Standard leader lower part	t	0.7
6 m leader extension	t	1.5
8 m leader extension	t	2.4
Leader top	t	1.7
Short leader lower part	t	0.3

^{*} Transport length folding leader

Options

Adapter for casing oscillator	t	8.0
Concrete supply line	t	0.6
All round platform with railings	t	0.4

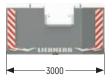




Counterweight Weight



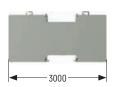
t 5.0

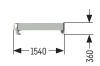




Counterweight

Weight t 8.0

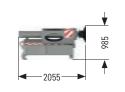




Intermediate slab

Weight t 5.0





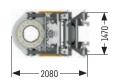
Counterweight with rear support unit

Weight t 8.0









BAT 250

Transport weight t 5.3

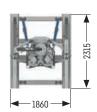
BAT 250 with adapter for drilling axis 1400 mm

Transport weight t 6.4







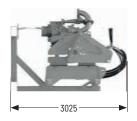


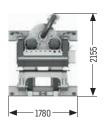
MA 180

Transport weight t 5.6

DBA 90

Transport weight t 5.7





DHR 110

Transport weight t 5.4

Kelly drilling

Standard

Standard (large drilling axis)





Performance data

remonitative data			
Rotary drive - torque	kNm	252	
Rotary drive - speed	rpm	58	
		Drilling axis 900mm	Drilling axis 1400 mm
Max. drilling diameter cased*	mm	1200	2200
Max. drilling diameter uncased	mm	1500	2500
Max. drilling diameter uncased with short leader lower part	mm	2700	3300

 $Above \ applications \ are \ sample \ illustrations. \ Other \ drilling \ diameters \ available \ on \ request.$

^{*} Depending on casing driver configuration

Drilling depths with Low Head and standard leader

Technical data Kelly bars

			Drilling depths							
	Kelly bars			Low	Head		Standard			
Model	Length A [mm]	Weight [t]	X [m]	Depth [m]		X [m]		Depth [m]	
			900	1400	900	1400	900	1400	900	1400
20/3/18	7800	3.4	5.4	5.0	16.6	17.1	11.4	11.0	16.6	17.1
20/3/21	8950	4.0	4.2	3.9	19.6	20.1	10.2	9.9	19.6	20.1
20/3/24	9950	4.4	3.21	2.9	22.6^{1}	23.1	9.2	8.9	22.6	23.1
20/3/27	10800	4.6	2.21	1.9^{1}	25.6 ¹	26.11	8.2	7.9	25.6	26.1
20/3/30	11800	4.9	1.41/2	1.0^{1}	28.61/2	29.11	7.4	7.0	28.6	29.1
20/3/33	12800	5.2	0.41/2	-	31.61/2	-	6.4	6.0	31.6	32.1
20/4/36	11265	6.2	1.91	1.5^{1}	34.6 ¹	35.1^{1}	7.9	7.5	34.6	35.1
20/4/42	12855	6.9	0.31/2	-	40.71/2	-	6.3	6.0	40.7	41.2
20/4/48	14200	8.2	-	-	-	-	4.9	4.5	46.6	47.1
20/4/54	15855	8.6	-	-	-	-	3.3 ¹	3.0	52.71	53.2

 $[\]overline{\ }^{1}$ When using a short leader lower part an assist crane is required for installation.

Drilling axis 900 mm
Drilling axis 1400 mm

Other Kelly bars available on request

When using a casing oscillator (standard 118/120 KL), value X must be reduced by 1200 mm.

Other casing oscillators available on request

When using a Kelly bar guide, value X has to be reduced by 1150 mm for a drilling axis of 900 mm, and by 1550 mm for a drilling axis of 1400 mm.

When using a short leader lower part the drilling depth is reduced by 2000 mm for a drilling axis of 900 mm, and by 2500 mm for a drilling axis of 1400 mm.

Length of drilling tool 1900 mm

Drilling depths with Ultra Low Head

Technical data Kelly bars

			Drilling depths with short leader lower part							
	Kelly bars			Leader top	horizontal			Leader top raised		
Model	Length A [mm]	Weight [t]	Х	[m]	Dept	:h [m]	X	[m]	Dept	h [m]
			900	1400	1100	1400	900	1400	900	1400
20/3/15	6970	3.2	2.32	2.32	10.42	10.3 ²	3.2 ²	3.2 ²	10.42	10.32
20/3/18	7800	3.4	1.42	1.42	13.4^{2}	13.3^{2}	2.42	2.42	13.4^{2}	13.3^{2}
20/3/21	8950	4.0	-	-	-	-	1.22	1.22	16.4^{2}	16.3^{2}
					rilling dept	ths with sta	ndard lead	er lower pa	rt	
20/3/15	6970	3.2	2.31	2.3	12.4^{1}	12.9	3.2	3.2	12.4	12.9
20/3/18	7800	3.4	1.42	1.4^{1}	15.4^{2}	15.9^{1}	2.42	2.4	15.4^{2}	15.9
20/3/21	8950	4.0	-	-	-	-	1.22	1.22	18.4^{2}	18.9 ²

 $^{^{\}mathrm{1}}$ Installation of Kelly bar with raised leader top

Drilling axis 900 mm
Drilling axis 1400 mm

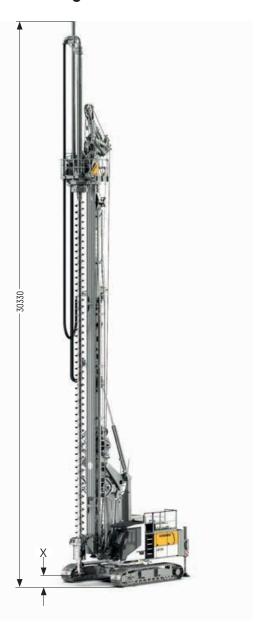
Other Kelly bars available on request Values indicated for minimum radius Length of drilling tool 710 mm

² Installation only possible using auxiliary equipment

² Installation only possible using auxiliary equipment

Continuous flight auger drilling

Folding leader



Performance data

Rotary drive - torque	kNm	230		
Rotary drive - speed	rpm	58		
Max. drilling diameter*	mm	1000		
		Low Head	Standard	Folding leader
Drilling depth without Kelly extension	m	10.1	16.1	18.1
Drilling depth with 6 m Kelly extension	m	16.1	22.1	24.1
Max. pull force	kN	700	700	700

 $Above \ drilling \ depths \ take \ into \ account \ that \ an \ auger \ cleaner \ is \ used \ and \ the \ cardan \ joint \ has \ been \ removed.$

Above drilling depths are valid for the use of standard tools and for the X value of 475 mm (see above illustration).

^{*} Other drilling diameters available on request

Full displacement drilling

Folding leader



Performance data

Rotary drive - torque	kNm	230		
Rotary drive - speed	rpm	58		
Max. drilling diameter*	mm	500		
		Low Head	Standard	Folding leader
Drilling depth without Kelly extension	m	10.6	16.6	18.6
Drilling depth with 6 m Kelly extension	m	16.6	22.6	24.6
Max. pull force	kN	700	700	700

Above drilling depths are valid for the use of standard tools and for an X value of 665 mm (see above illustration).

* Other drilling diameters available on request

Double rotary drilling

DBA 90



Performance data

Rotary drive I - torque	kNm	0-90		
Rotary drive I - speed	rpm	0-32		
Rotary drive II - torque	kNm	0-68		
Rotary drive II - speed	rpm	0-44		
Max. drilling diameter*	mm	620		
		Low Head	Standard	Folding leader
Drilling depth	m	10.4	16.4	18.4
Max. pull force	kN	300	300	300

Above drilling depths are valid for the use of standard tools and for an X value of 885 mm (see above illustration). Due to differences in the max. admissible load capacities, the combinations of drilling depth and drilling diameter may be limited.

^{*} Other drilling diameters available on request

Soil mixing

MA 180 / BAT 250





Performance data MA 180

Rotary drive - torque	kNm	0-165		
Rotary drive - speed	rpm	0-80		
Max. mixing diameter*	mm	1500		
		Low Head	Standard	Folding leader
Mixing depth	m	11.0	17.0	19.0
Mixing depth with 6 m Kelly extension	m	17.0	23.0	25.0
Max. pull force	kN	700	700	700

Performance data BAT 250

Rotary drive - torque	kNm	230		
Rotary drive - speed	rpm	58		
Max. mixing diameter*	mm	1500		
		Low Head	Standard	Folding leader
Mixing depth	m	10.6	16.6	18.6
Mixing depth with 6 m Kelly extension	m	16.6	22.6	24.6
Max. pull force	kN	700	700	700

Above mixing depths are valid for the use of standard tools and for an X value of 300 mm for MA 180, and $665 \, \text{mm}$ for BAT 250 (see above illustration).

 $[\]ensuremath{^*}$ Other mixing diameters available on request

Down-the-hole drilling

DHR 110





Performance data DHR 110

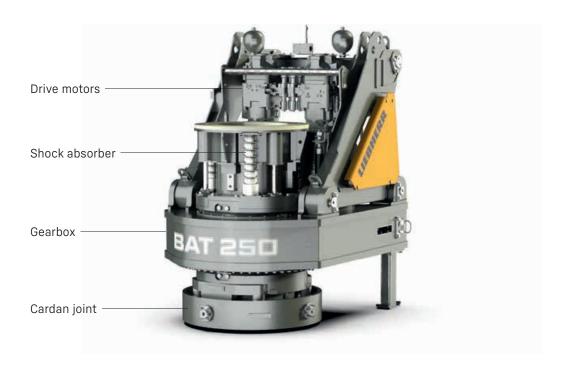
1 CHOTHIGHEC Gata DHK 110				
Rotary drive - torque	kNm	106		
Rotary drive - speed	rpm	41		
		Low Head	Standard	Folding leader
Drilling depth	m	10.7	16.7	18.7
Folding function	0	0-90	0-90	0-90
Max. pull force	kN	600*/350**	600*/350**	600*/350**

 $Above \ drilling \ depths \ are \ valid \ for \ the \ use \ of \ standard \ tools \ and \ for \ an \ X \ value \ of \ 500 \ mm \ (see \ above \ illustration).$

^{*} Max. pull force recovery mode

^{**} Max. pull force drilling operation

BAT 250



Kelly shock absorber:

- Newly developed Kelly shock absorber for highest demands
- Possibility of adjusting the strength of the Kelly shock absorber for different Kelly bar weights

Automatic gearbox for best operating comfort:

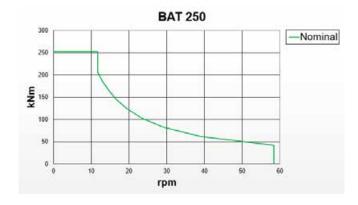
- No stopping required to change gears
- No interruption of the drilling process
- Continuous optimization of speed

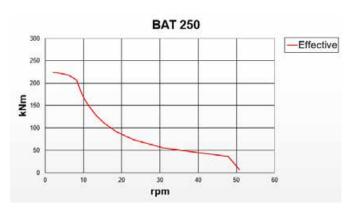
Highest availability through easy set-up:

- No mechanical shift gearbox
- -Low maintenance requirements

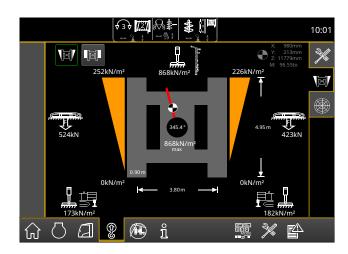
Flexibility through modular design:

- -Exchangeable cardan joint for other casing drivers
- -Exchangeable drive adapters for use of other Kelly bars
- Quickly exchangeable equipment for other methods of operation





Ground pressure visualization





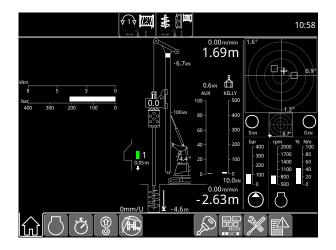
Features:

- -The actual ground pressure is calculated in real time
- -The maximum admissible ground pressure can be individually predefined
- -The utilization is continuously calculated and displayed on the monitor in the operator's cabin
- Audible and visual warnings when the predefined values are approached

Your benefits:

- Increased safety on the jobsite due to consideration of prevailing ground conditions
- Higher operator comfort thanks to clearly displayed information and warning signals
- Prevention of critical or stressful situations before they occur
- -User-friendly and intuitive handling in the operator's cabin

Kelly visualization

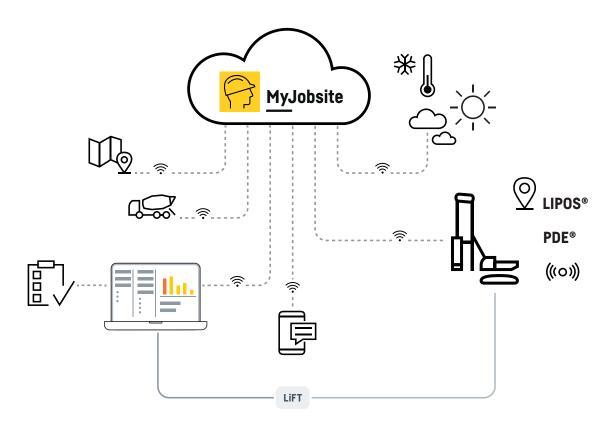


Your benefits:

- -Time saving: the operator no longer needs to search for the interlocking recesses
- Higher availability: the machine needs less repair and maintenance work
- More safety: correct locking prevents damage to the Kelly bar
- -Cost reduction: smooth operation results in higher performance and less wear

Digitalization in deep foundation work

As deep foundation expert, Liebherr has created a combination of the most diverse assistance systems and software solutions in order to record and evaluate complex processes and to be able to provide the corresponding evidence.



LIPOS - Liebherr positioning system

Using pre-installed components, LIPOS enables the direct integration of machine control systems from Trimble and Leica. These systems are based on modern DGNSS technology (Differential Global Navigation Satellite System) and so achieve the best possible conditions for a precise and efficient positioning of Liebherr machines and their attachment tools.

PDE

All working processes can be electronically recorded and visualized using the process data recording system PDE. The system is operated and displayed on the PDE touch-screen in the operator's cab. PDE records operating data from the Litronic control system, as well as data from external sensors.

MyJobsite

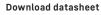
Using the MyJobsite software solution all relevant process, machine, construction site and positioning data (LIPOS) can be recorded, displayed, analysed, managed

and evaluated in one central location. The collected data can be accessed via a web browser when an internet connection is active.

With the recorded PDE data, such as the driving progress of the pile per blow, the total number of blows, or the impact frequency per minute, a driving protocol is automatically generated as proof of quality directly after completion of a work process. The parameters of the driving protocol can be defined and assigned in advance. Using the templates saves a lot of time when creating the protocols.

MyJobsite is THE tool for quality control and documentation. The deluge of data, which s accrued each day from a wide variety of sources on the jobsite, can be recorded precisely and processed in an informative manner. Unpopular bureaucratic work is kept to a minimum and the amount of time required for it is significantly reduced. At the same time, the quality of administration work is maximised.







Please contact us.